

Resource reasoning in temporal planning

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A decorative graphic consisting of several horizontal lines of varying lengths and colors (teal, light blue, white) extending from the right side of the slide.

Obsah

- **Úvod**
 - Plánování s časem a zdroji
 - Motivace
- **Práce s časem**
 - algebry, CSP, STP, DTP, exekuce
- **Práce se zdroji**
 - Taxonomie
 - Unární
 - Diskrétní
 - Rezervoáry

Plánování s časem a zdroji

- V modelu světa se snažíme najít plán, který z počátečního stavu světa dosáhne cíle.
- Plánování s explicitním časem.
 - Akce mají dobu trvání, jsou rozvrženy v čase a jejich efekty mohou interferovat.
- Proč zdroje v plánování?
 - Přenesením zdrojů do plánování můžeme sledovat kritéria zajímavá pro rozvrhování již během konstrukce plánu.

Motivace

- **Autonomní systémy**
 - Trex, Mars Rover, MrSPOCK
 - Armáda – letadla, družice
- **Efektivita**
 - Rescue operation
 - Manufacturing
 - Logistika
- **„Strong AI“**
 - Být schopen naplánovat cestu k dosažení svých cílů je klíčové.

Příklady

- **Manufacturing:**
 - *A grinding operation requires a grinding machine. The **grinding machine** can perform only one operation at a time. Only one grinding machine is available in the shop.*
- **Project Management:**
 - *In a web site development project, the task of testing browsers compatibility requires an effort of 6 person-months of a **quality engineer**. 5 quality engineers are available.*
- **Satellite:**
 - *When the satellite is not within range of a receiving station, it can store images on an onboard **solid-state memory** that provides a capacity of 90 Gbits (550 images).*
- **Crisis Management:**
 - *An aircraft B737-200 has a **capacity** to evacuate at most 120 people. Maximum **cargo loading** is 3,400kg for a **volume** of 14.3 m³. **Maximal range** of the aircraft is 2480km.*

Čas na čaj

- Zajímá nás konzistence a řešení.
- Kvalitativně
 - **Point Algebra**
 - $A \{<, =, >\} B$
 - Řešení v polynomiálním čase.
 - **Interval Algebra**
 - 13 vztahů mezi intervaly.
 - NP-těžké.
- Kvantitativně
 - **STP, DTP**

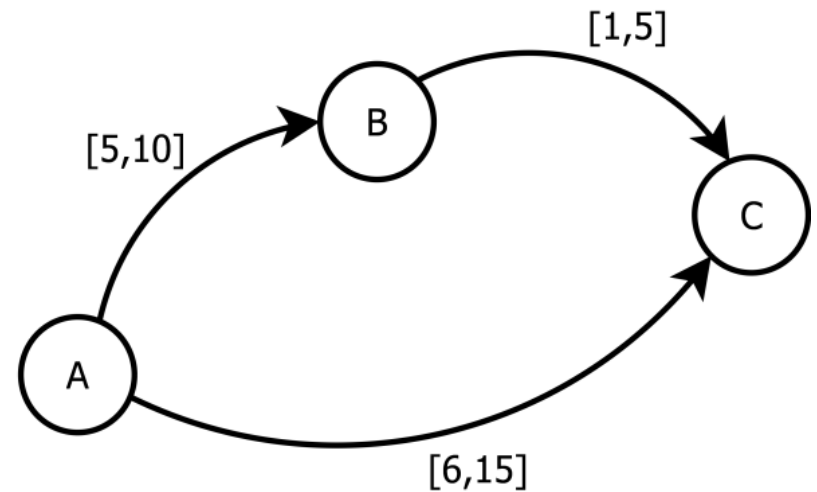
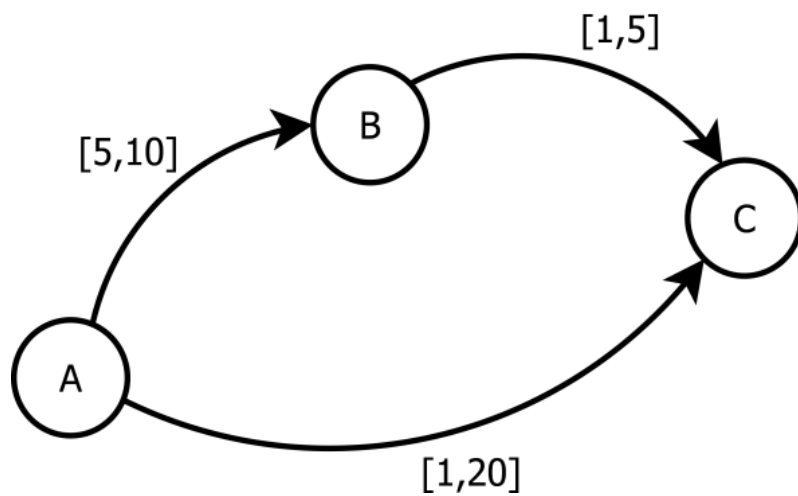
Constraint Satisfaction Problem

- **Definice:**
 - Proměnné: $X = \{x_1, \dots, x_n\}$
 - Domény: $D = \{d_1, \dots, d_n\}$
 - Podmínky: $C = \{c_1, \dots, c_m\}$
- (Instance) řešení:
 - Přiřazení hodnot proměnným za splnění podmínek.
- Způsob řešení:
 - Prohledávání, propagace podmínek.
 - NP-úplné !

Simple Temporal Problem

- Množina časových proměnných, reprezentujících události.
 - $\{A, B, C, \dots\}$
- Množina binárních podmínek
 - $x \leq B - A \leq y$, neboli B se stane nejdříve za x a nejpozději za y časových jednotek po A.
- Proměnné a podmínky tvoří časovou síť (STN)
 - Síť lze minimalizovat a odvodit tak mezní podmínky mezi všemi páry proměnných.
 - $O(n^3)$

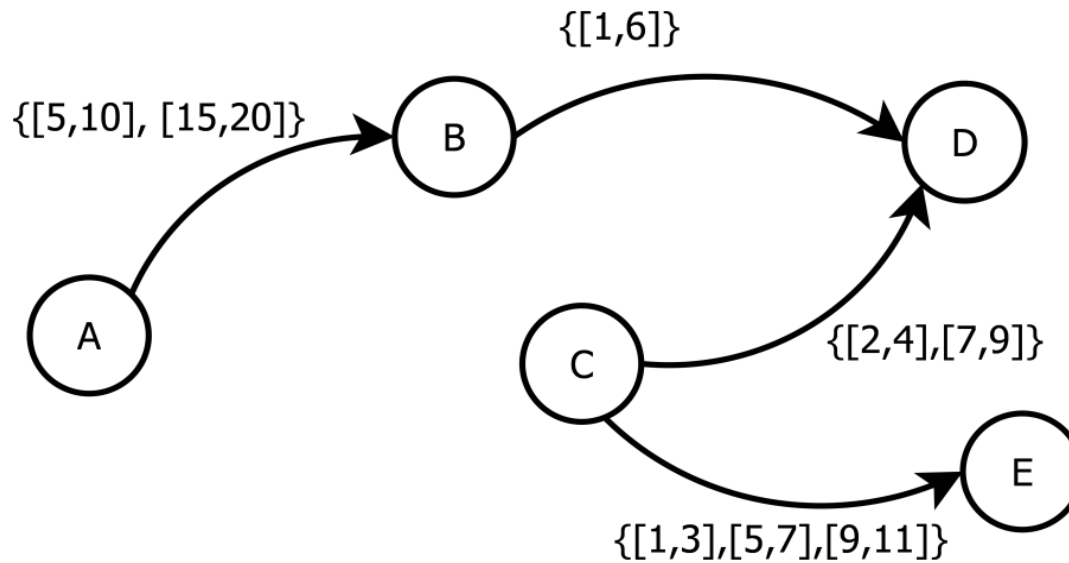
Simple Temporal Network



Disjunctive Temporal Problem

- Množina časových proměnných, reprezentujících události.
 - $\{A, B, C, \dots\}$
- Množina binárních podmínek
 - Každá podmínka je tvořena disjunkcí podmínek $(x_1 \leq B - A \leq y_1), \dots, (x_k \leq B - A \leq y_k)$
 - NP-těžké už pro binární disjunkty.

Disjunctive Temporal Network



Exekuce

- **Naivní modely**
 - **STP & DTP dispatch**
- **Kontrolovatelnost**
 - **Silná, slabá, dynamická**

Taxonomie zdrojů

- Based on the way a resource is consumed and produced, we distinguish between resources that are:
 - *Consumable*
 - when the resource is only consumed in the system; e.g. fuel in a car, which cannot be refuelled.
 - *Producible*
 - when the resource is only produced in the system; e.g. some waste-product of industrial system.
 - *Replenishable*
 - when the resource can be both consumed and produced in the system; e.g. fuel in a car, which can be refuelled.
 - *Reusable*
 - when production and consumption must happen in tandem, e.g. for each consumption there exists a production.

Taxonomie

- Based on quantities that can be consumed or produced by a resource we distinguish between resources that are:
 - *Discrete*
 - when the resource is consumed, produced, or used in discrete quantities; e.g. sitting rooms in a car.
 - *Continuous*
 - when the resource is consumed, produced, or used in continuous quantities; e.g. fuel in a car.

Taxonomie

- Based on properties of capacity of a resource, we distinguish between:
 - *Single-capacity*
 - when the resource can be thought of as one unit, which must be consumed as a whole.
 - *Multi-capacity*
 - when the resource represents multiple units which can be used or consumed by different operations.
 - *Fixed Capacity*
 - when the capacity does not change over time.
 - *Variable Capacity*
 - when the capacity of the resource is a function of time; e.g. a battery whose capacity degrades.

Taxonomie

- Additionally we distinguish between resources that are:
 - *Shared*
 - when multiple activities can access the resource.
 - *Exclusive*
 - when only a single activity can access the resource.
 - *Single-dimensional*
 - when only a single level of the resource is considered; e.g. the number of places in an elevator.
 - *Multi-dimensional*
 - when multiple levels of the resource are considered; e.g. an elevator with the maximal allowed number of passengers and the maximal allowed weight.

Zdroje

- **Unary resource:**
 - Resource of capacity 1. Two activities requiring the same unary resource cannot overlap
- **Discrete resource:**
 - Resource of capacity Q . Activities requiring the same discrete resource can overlap provided the resource capacity Q is not exceeded
- **Reservoir:**
 - Resource of capacity Q and initial level L ; Activities may consume or produce the reservoir. The level of the reservoir over time must be kept in the interval $[0, Q]$

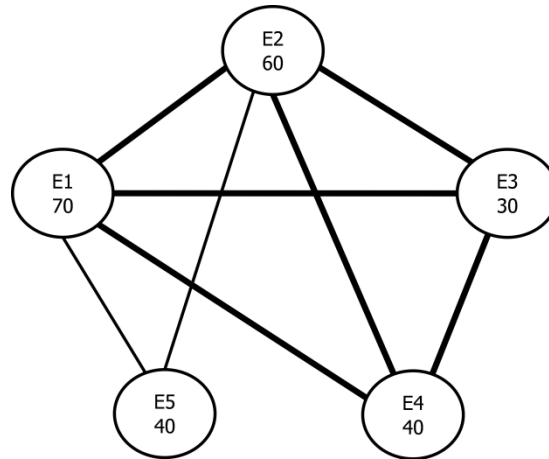
Techniky

- **Disjunctive constraints**
 - $end(A) < start(B)$ OR $start(B) > end(A)$
- **Edge-finding**
 - detects situations where a given activity A cannot execute after any activity in a set Ω because there would not be enough time to execute all the activities in $\Omega \cup A$ between the earliest start time of activities in $\Omega \cup A$ and the latest end time of activities in $\Omega \cup A$. When such a situation occurs, it means that A must execute before all the activities in Ω and it allows computing a new valid upper bound for the end time of A .
- **Energy constraint**
 - A typical example of energetic reasoning consists in finding pairs of activities (A, B) on a unary resource such that ordering activity A before B would lead to a dead end because the unary resource would not provide enough “energy” between the earliest start time of A and the latest end time of B to execute A , B and all the other activities that necessarily need to partly execute on this time window.
- **Energy precedence constraint**
- **Balance constraint**

Precedence graph

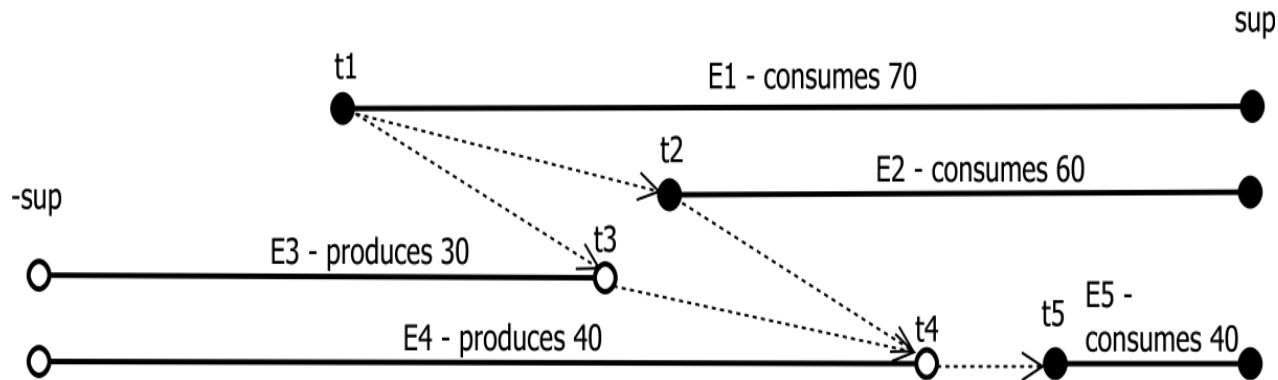
- Nodes correspond to requirements
- Edge between two nodes exists iff the time intervals of requirements corresponding to nodes *may* overlap.

Precedence graph



The precedence graph for a multi-capacity reusable resource. The capacity of the resource is 170 (capacity of the reservoir + requirements of all production events). Lines represent potential intersection of the time intervals of the requirements. Bold lines represent the complete subgraph that overconsumes the resource ($70+40+30+60 > 170$).

Transformace na diskrétní zdroj



- Transformation of the reservoir into a multi-capacity reusable resource. Dotted lines represent temporal relation *necessarily before*.

Zdroje

- **Temporal and resource reasoning for planning, scheduling and execution**, Nicola Muscettola, Martha Pollack, ICAPS2005
- **Algorithms for propagating resource constraints in AI planning and scheduling: Existing approaches and new results**, Philippe Laborie, Artificial Intelligence, 2003
- **Constraint-based scheduling and planning**, P. Baptiste, P Laborie, Hand of Constraint Programming, 2006
- **Integrating Time and Resources into Planning**, F. Dvořák, R. Barták, ICTAI 2010